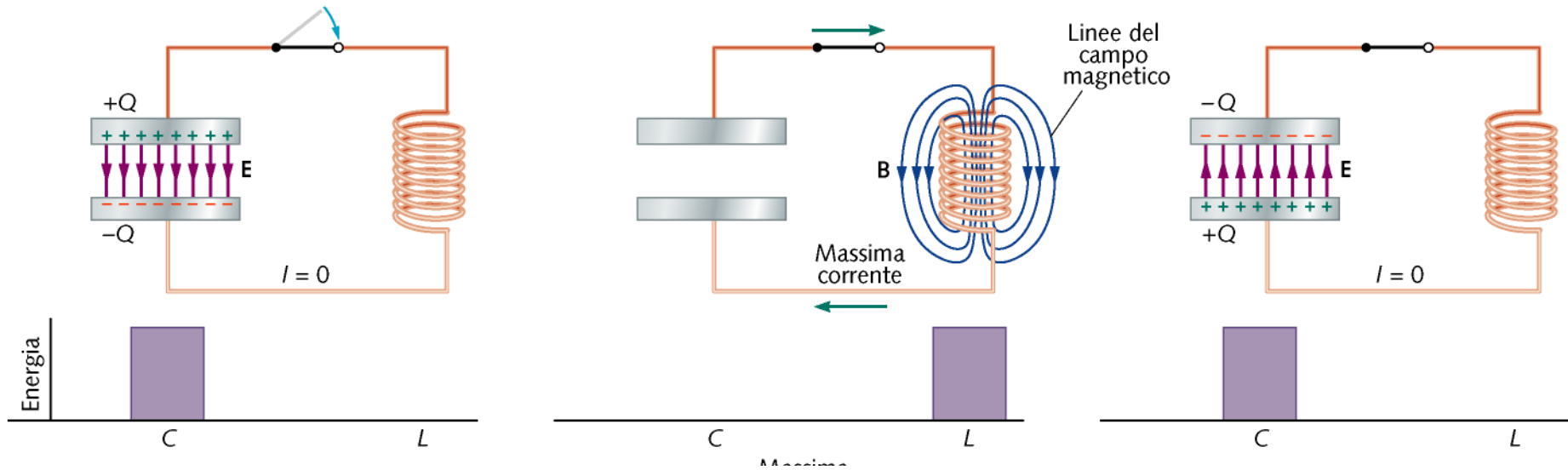


Circuito LC



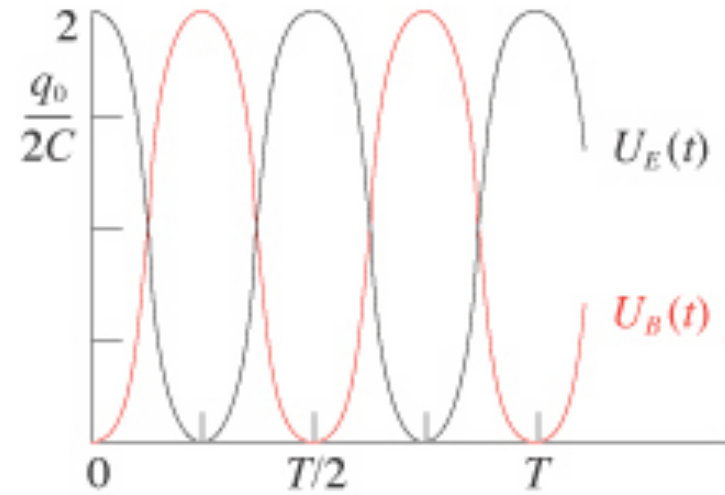
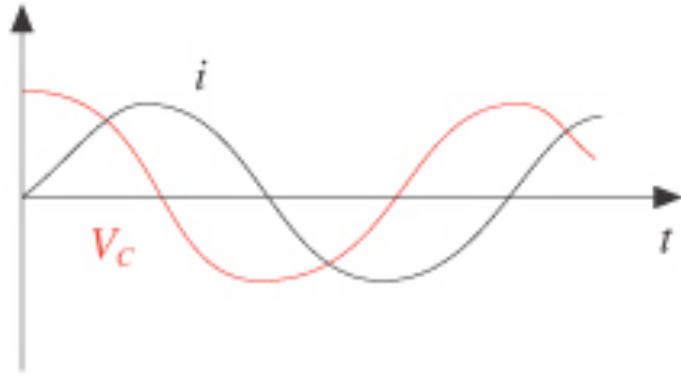
$$L \frac{dI}{dt} + \frac{q}{C} = 0$$

$$L \frac{d^2 q}{dt^2} + \frac{q}{C} = 0$$

$$q(t) = Q \cos(\omega t + \phi)$$

$$\omega = \frac{1}{\sqrt{LC}}$$

$$\frac{1}{\sqrt{[H][C]}} = \sqrt{\frac{[A][V]}{[s][V][Q]}} = [s^{-1}]$$



$$V(t) = \frac{q}{C} = \frac{Q}{C} \cos(\omega t + \phi)$$

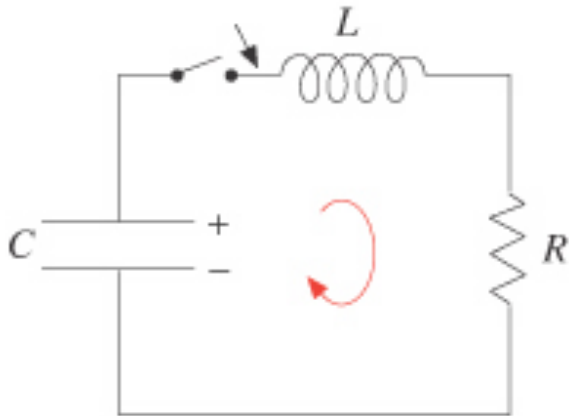
$$I(t) = \frac{dq}{dt} = -Q\omega \sin(\omega t + \phi)$$

$$U_E(t) = \frac{q^2}{2C} = \frac{Q^2}{2C} \cos^2(\omega t + \phi)$$

$$U_B(t) = \frac{LI^2}{2} = \frac{LQ^2\omega^2}{2} \sin^2(\omega t + \phi) = \frac{LQ^2}{2LC} \sin^2(\omega t + \phi)$$

$$U_E(t) + U_B(t) = \frac{Q^2}{2C}$$

Circuito RLC

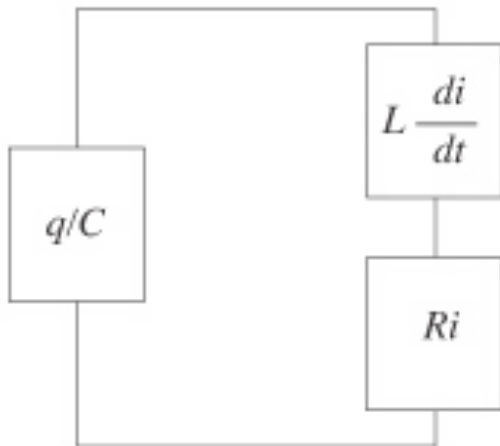


$$L \frac{dI}{dt} + \frac{q}{C} + RI = 0$$

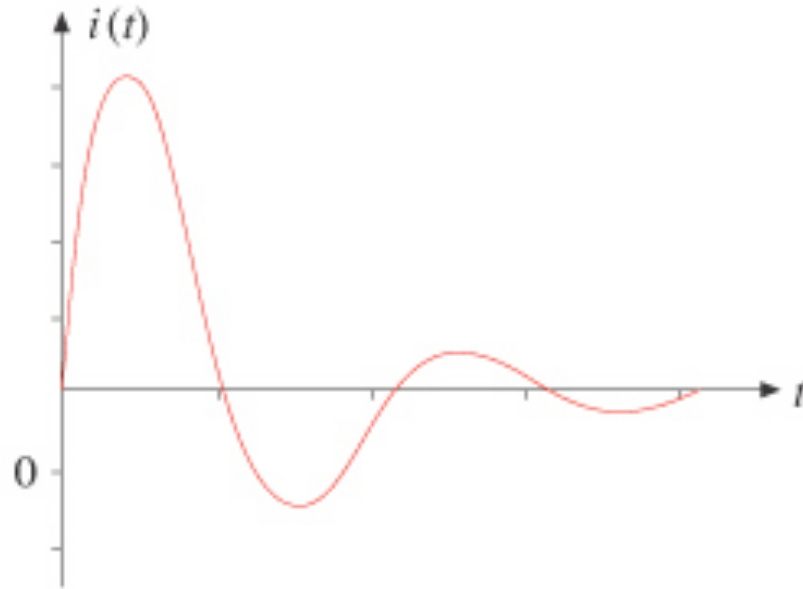
$$L \frac{d^2 q}{dt^2} + R \frac{dq}{dt} + \frac{q}{C} = 0$$

$$q(t) = Q e^{-\frac{R}{2L}t} \cos(\omega' t + \phi)$$

$$\omega' = \sqrt{\omega^2 - \left(\frac{R}{2L}\right)^2}$$

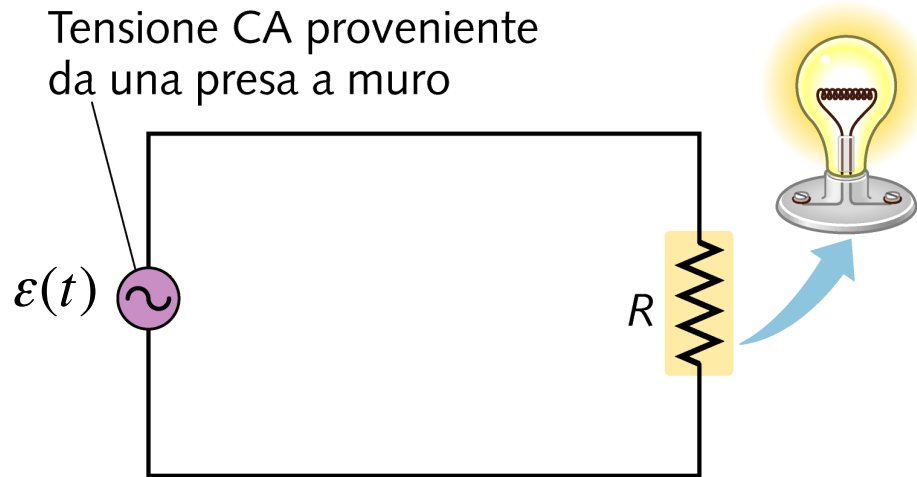


Circuito RLC



$$E_c = \frac{q^2}{2C} = \frac{Q^2}{2C} e^{-\frac{R}{L}t} \cos^2(\omega' t + \phi)$$

Carico resistivo con corrente alternata



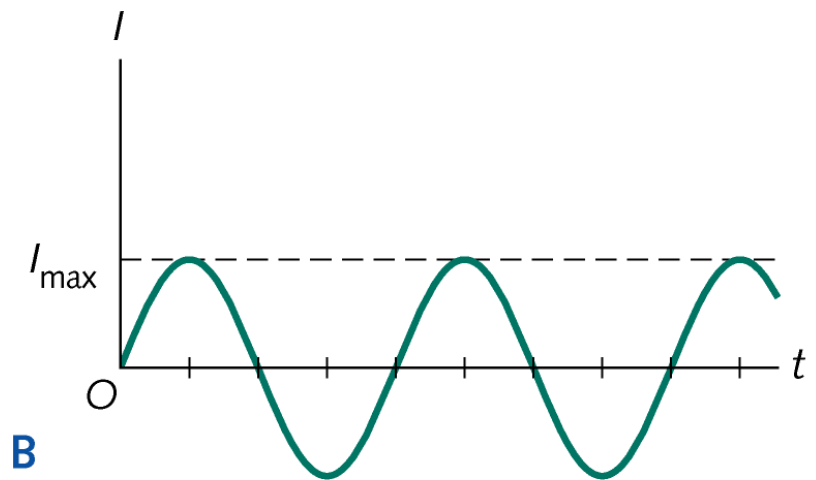
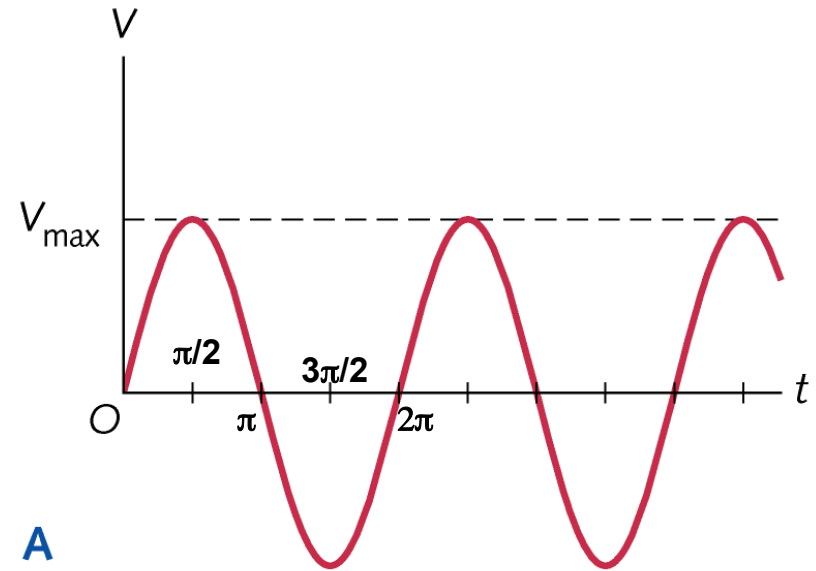
$$\varepsilon(t) = V_{MAX} \sin(\omega t) \quad \text{f.e.m. alternata}$$

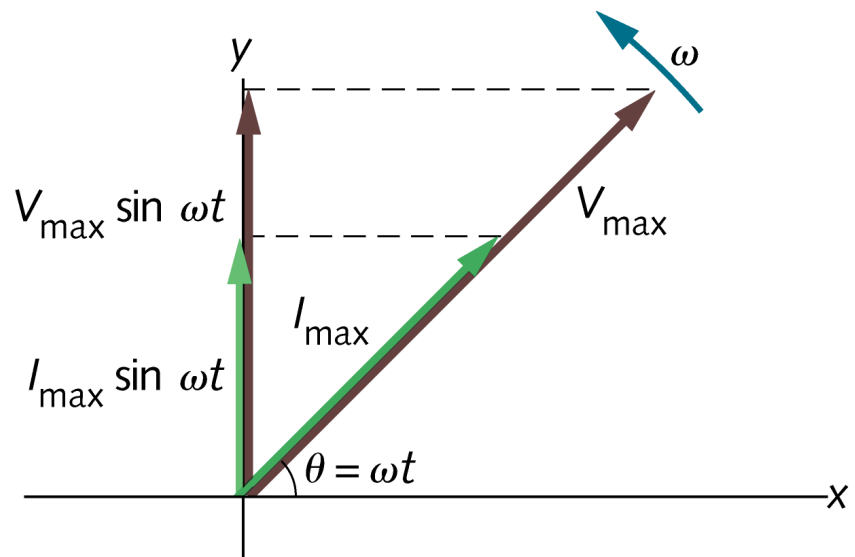
$$V_R = iR = \varepsilon(t)$$

$$V_R(t) = V_{MAX} \sin(\omega t)$$

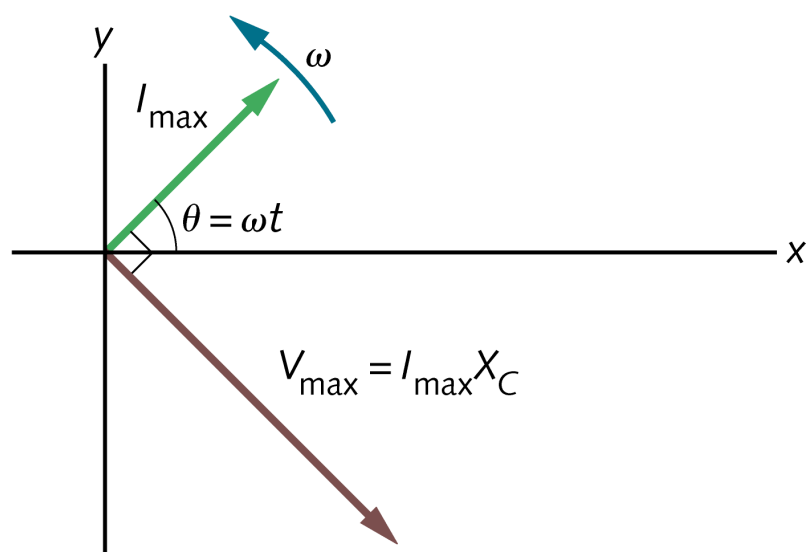
$$I(t) = \frac{V_{MAX}}{R} \sin(\omega t) = I_{MAX} \sin(\omega t)$$

$$I(t) = \frac{V(t)}{R}$$

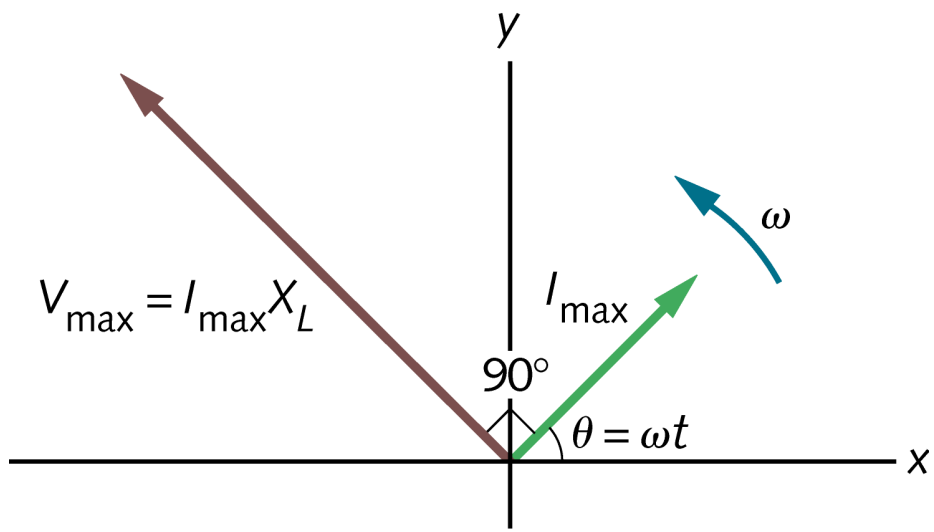




Carico resistivo

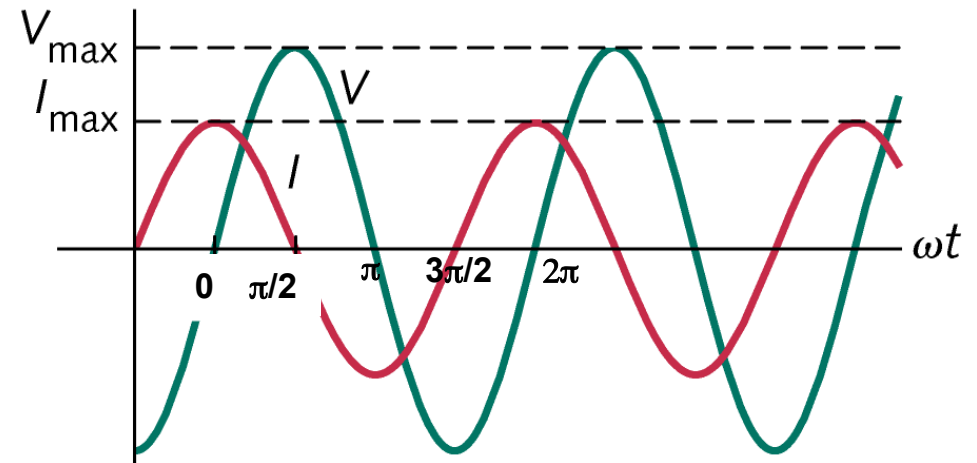
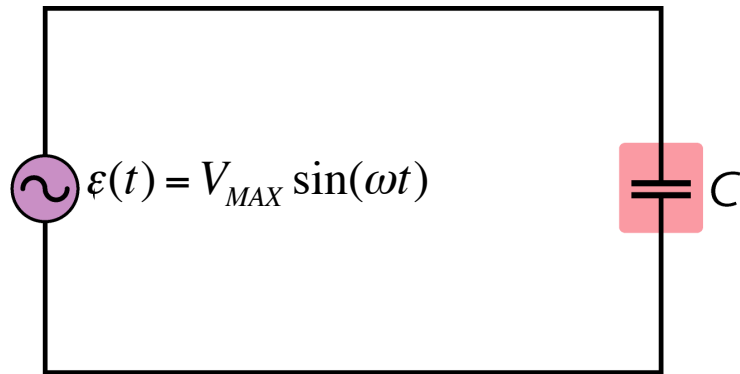


Carico capacitivo



Carico induttivo

Carico capacitivo con corrente alternata



$$V_C = \frac{q}{C} = \varepsilon(t)$$

$$V_C(t) = V_{MAX} \sin(\omega t)$$

$$q(t) = CV_C(t) = CV_{MAX} \sin(\omega t)$$

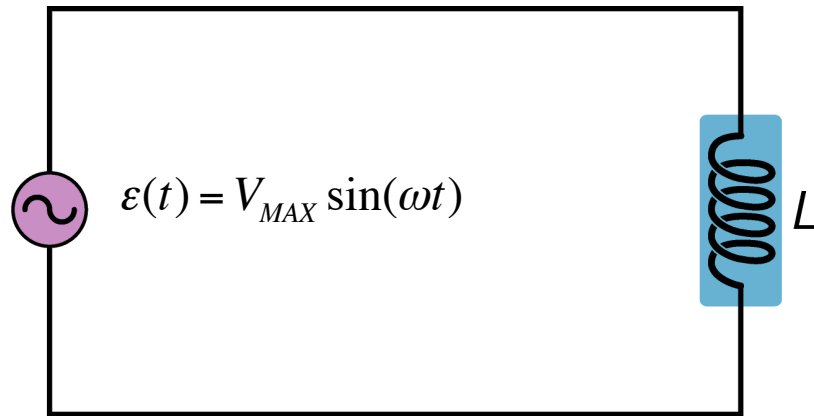
$$I(t) = \frac{dq}{dt} = -\omega CV_{MAX} \cos(\omega t) = \omega CV_{MAX} \sin\left(\omega t + \frac{\pi}{2}\right)$$

$$I_{MAX} = \frac{V_{MAX}}{X_C}$$

$$X_C = \frac{1}{\omega C} \text{ Reattanza capacitiva}$$

$$\frac{[s]}{[F]} = \frac{[s][V]}{[C]} = \frac{[V]}{[A]} = [\Omega]$$

Carico induttivo con corrente alternata



$$V_L = L \frac{dI}{dt} = \varepsilon(t)$$

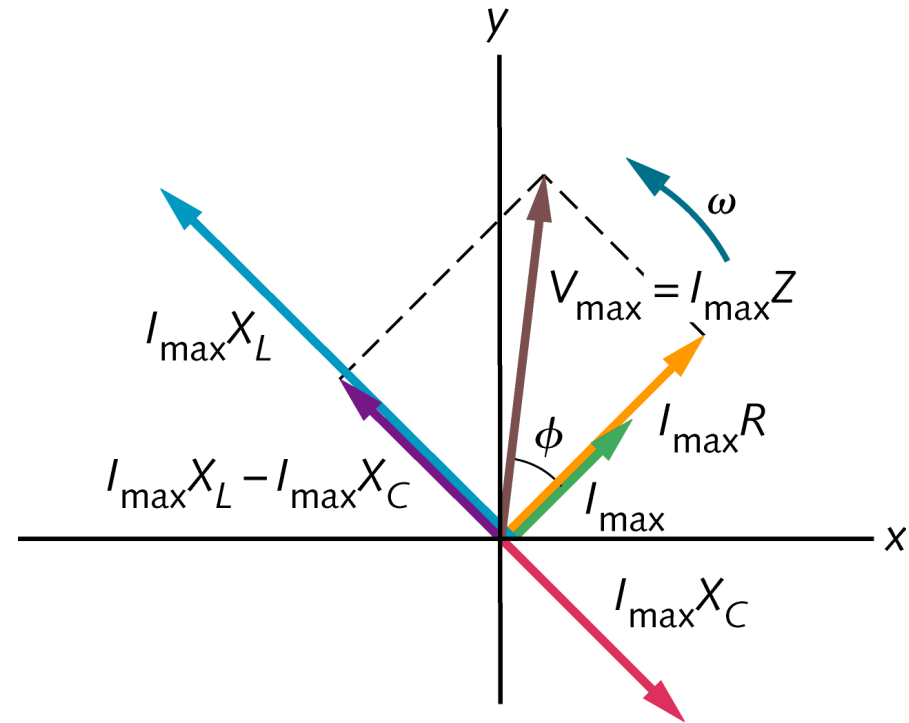
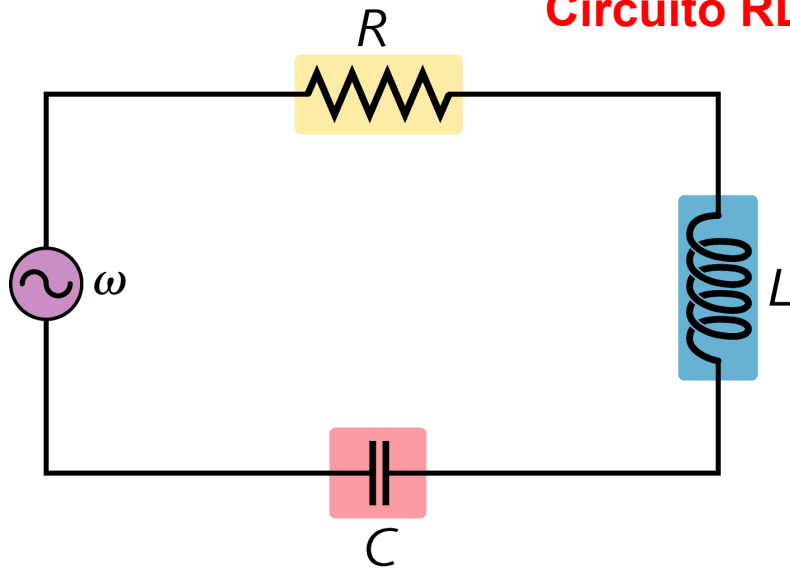
$$V_L(t) = V_{MAX} \sin(\omega t)$$

$$I(t) = \int dI(t) = \frac{V_{MAX}}{L} \int \sin(\omega t) dt = -\frac{V_{MAX}}{\omega L} \cos(\omega t) = \frac{V_{MAX}}{\omega L} \sin\left(\omega t - \frac{\pi}{2}\right)$$

$$I_{MAX} = \frac{V_{MAX}}{X_L}$$

$$X_L = \omega L \quad \text{Reattanza induttiva} \quad \frac{[H]}{[s]} = \frac{[s][V]}{[A][s]} = \frac{[V]}{[A]} = [\Omega]$$

Circuito RLC in corrente alternata



$$\varepsilon^2 = V_R^2 + (V_L - V_C)^2$$

$$\varepsilon^2 = (IR)^2 + (IX_L - IX_C)^2$$

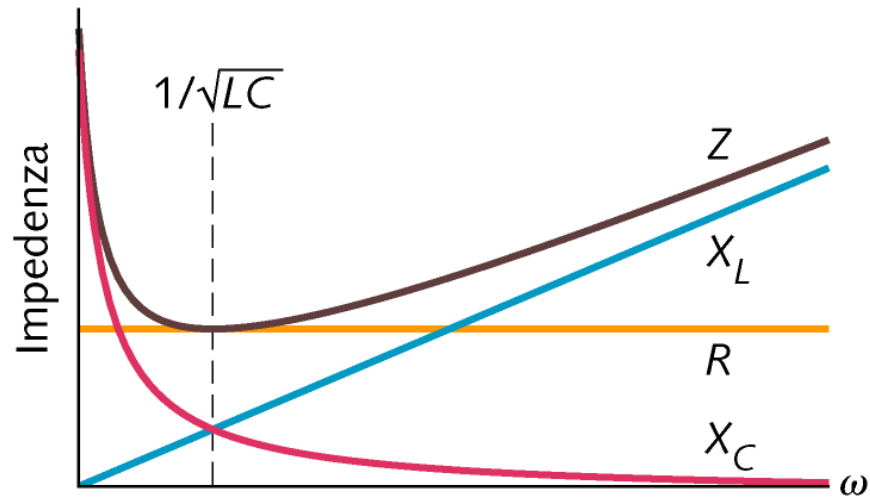
$$I = \frac{\varepsilon}{\sqrt{R^2 + (X_L - X_C)^2}} = \frac{\varepsilon}{\sqrt{R^2 + \left(\omega L - \frac{1}{\omega C}\right)^2}} = \frac{\varepsilon}{Z}$$

$$Z = \sqrt{R^2 + \left(\omega L - \frac{1}{\omega C}\right)^2} \quad \text{impedenza}$$

$$I = I_{MAX} \sin(\omega t - \phi)$$

$$\tan \phi = \frac{X_L - X_C}{R} \quad \text{fase}$$

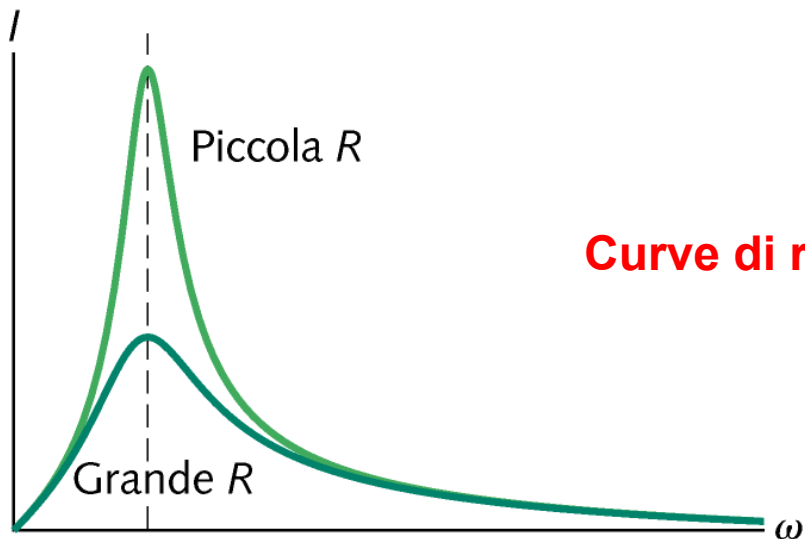
Andamento di Z , X_L , X_C , R in funzione di ω



A

Condizione di risonanza

$$\omega = \frac{1}{\sqrt{LC}}$$



Curve di risonanza

B

Potenza nei circuiti a corrente alternata

$$P(t) = I^2 R = I_{MAX}^2 R \sin^2(\omega t - \phi)$$

$$\bar{P} = \int P(t) dt = I_{MAX}^2 R \frac{1}{2\pi} \int_0^{2\pi} \sin^2(\omega t - \phi) dt = \frac{I_{MAX}^2 R}{2}$$

$$I_{eff} = \frac{I_{MAX}}{\sqrt{2}}$$

$$\bar{P} = I_{eff}^2 R = I_{eff} I_{eff} R = I_{eff} \frac{V_{eff}}{Z} R = I_{eff} V_{eff} \frac{R}{Z} = I_{eff} V_{eff} \cos \phi$$